
6x86 BIOS WRITER'S GUIDE

1.0 Introduction**1.1 Scope**

This document is intended for STST6x86 system BIOS writers. It is not a stand alone document but supplements other SGS-THOMSON and STST6x86 documentation including: STST6x86 Data Book, STST6x86/PENTIUM(P54C) Bus Interface Differences, SGS-THOMSON SMM Programmer's Guide. This document includes recommendations for STST6x86 detection and STST6x86 configuration register settings. Configuration register settings described in this document apply to STST6x86 step A and higher.

The recommended settings are optimized for both performance and compatibility in a Windows95, Plug and Play (PnP), PCI-based system. Issues regarding optimum performance, CPU detection, chipset initialization, memory discovery, I/O recovery time, and others are described in detail.

1.2 STST6x86 Configuration Registers

The STST6x86 uses on-chip configuration registers to control the on-chip cache, system management mode (SMM), device identification, and other STST6x86 unique features. The on-chip registers are used to activate advanced features including performance enhancements. These performance features may be enabled "globally" in some cases, or by a user-defined address region. The flexible configuration of the STST6x86 is intended to fit a wide variety of systems.

The Importance of Non-Cacheable Regions

The STST6x86 has eight internal user-defined Address Region Registers. Among other attributes, the regions define cacheability vs. non-cacheability of the address regions. Using this cacheability information, the STST6x86 is able to implement high performance features, that would otherwise not be possible. A non-cacheable region implies that read sourcing from the write buffers, data forwarding, data bypassing, speculative reads, and fill buffer streaming are disabled for memory accesses within that region. Additionally, strong cycle ordering is also enforced. Although negating KEN# during a memory access on the bus prevents a cache line fill, it does not fully disable these performance features. In other words, negating KEN# is NOT equivalent to establishing a non-cacheable region in the STST6x86.

2.0 Detecting a SGS-THOMSON STST6x86 CPU

STST6x86 detection must first be determined by the BIOS during Power-On Self Test using the method described in Section 2.1. Allowing STST6x86 detection using CPUID at runtime is covered in Section 2.4.

It is important to note that the STST6x86's CPUID instruction is disabled following reset. SGS-THOMSON's compatibility testing has found that some popular software does not correctly check the CPUID return values (e.g. Vendor Identification String and Family fields). This results in misidentification of CPU features which may cause a variety of runtime errors. By disabling the CPUID instruction, the STST6x86 CPU is assured to run code compatible with the 486 instruction set and programming model.

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2.1 Detecting a SGS-THOMSON CPU

Since CPUID is disabled by default, it cannot be used to identify the STST6x86 during BIOS POST. The correct method for detecting the presence of an STST6x86 microprocessor during BIOS POST is a two step process. First, a SGS-THOMSON brand CPU must be detected. Second, the CPU's Device Identification Registers (DIRs) provide the CPU model and stepping information. Alternate methods of detecting the CPU are not recommended. These include detection algorithms using the value of EDX following reset, and other signature methods of determining if the CPU is an 8086, 80286, 80386, or 80486.

Detection of a SGS-THOMSON brand CPU is implemented by checking the state of the undefined flags following execution of the divide instruction which divides 5 by 2 (5*2). The undefined flags in a SGS-THOMSON microprocessor remain unchanged following the divide. Alternate CPUs modify some of the undefined flags. Using operands other than 5 and 2 may prevent the algorithm from working correctly. Appendix A contains example code for detecting a SGS-THOMSON CPU using this method.

2.2 Detecting CPU Type and Stepping using DIRs

Once a SGS-THOMSON brand CPU is detected, the model and stepping of the CPU can be determined. All SGS-THOMSON CPUs contain Device Identification Registers (DIRs) that exist as part of the configuration registers. The DIRs for all SGS-THOMSON CPUs exist at configuration register indexes 0FEh and 0FFh. (See Chapter 3 for additional information.) Table 2-1 specifies the contents of the STST6x86 DIRs.

DIR0 bits [7:3] = 00110h indicate an STST6x86 CPU is present, DIR0 bits [2:0] indicate the core-to-bus clock ratio, and DIR1 contains stepping information. Clock ratio information is provided to assist calculations in determining bus frequency once the CPU's core frequency has been calculated. Proper bus speed settings are critical to overall system performance.

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Table 2.1 STST6x86 Device Identification Register

Register	Description	Bit Position	Contents	Core/Bus Clock Ratios
DIR0	CPU Model	7-0	30h or 32h	1/1
			31h or 33h	2/1
			35h or 37h	3/1
			34h or 36h	4/1
DIR1	Device Stepping	7-0	xxh	--

x = TBD

2.3 Determining ST6x86 Operating Frequency

Determining the operating frequency of the CPU is normally required for correct initialization of the system logic. Typically, a software timing loop with known instruction clock counts is timed using legacy hardware (the 8254 timer/counter circuits) within the PC. Once the operating frequency of the STST6x86's core is known, DIR0 bits (2:0) can be examined to calculate the bus operating frequency.

Careful selection of instructions and operands must be used to replicate the exact clock counts detailed in the Instruction Set Summary in the STST6x86 Data Book. An example code sequence for determining the STST6x86's operating frequency is detailed in Appendix B and Appendix C. The core loop uses a series of five IDIV instructions within a LOOP instruction. IDIV was chosen because it is an exclusive instruction meaning that it executes in the STST6x86 x pipeline with no other instruction in the y pipeline. This allows for more predictable execution times as compared to using non-exclusive instructions.

The STST6x86 instruction clock count for IDIV varies from 17 to 45 clocks for a doubleword divide depending on the value of the operands. The code example in the appendices uses "0" divided by "1" which takes only 17 clocks to complete. The LOOP instruction clock count is 1. Therefore, the overall clock count for the inner loop in this example is 86 clocks.

2.4 CPUID Instruction

The CPUID instruction is disabled following reset to improve compatibility with existing software. It can be enabled by setting the CPUIDEN bit in configuration register CCR4. It is recommended that all BIOS vendors include a CPUID enable/disable field in the CMOS setup to allow the end user to enable the CPUID instruction. CPUID must default to disabled and remain disabled unless enabled by the end user.

The CPUID instruction, opcode **0FA2h**, provides information indicating SGS-THOMSON as the vendor and the family, model, stepping, and CPU features. Additional documentation on the CPUID instruction and how alternate CPUs execute this instruction can be found in the Pentium Processor User's Manual, Volume 3, page 25-62; Pentium Processor User's Manual, Volume 1, Page 3-7; and Intel's application note AP-485.

The EAX register provides the input value for the CPUID instruction. The EAX register is loaded with a value to indicate what information should be returned by the instruction.

Following execution of the CPUID instruction with an input value of "0" in EAX, the EAX, EBX, ECX and EDX registers contain the information shown in Figure 2-1. EAX contains the highest input value understood by the CPUID instruction, which for the ST6x86 is "1". EBX, ECX and EDX contain the vendor identification string "CyrixInstead".

Following execution of the CPUID instruction with an input value of "1" loaded in EAX, EAX[15:0] will contain the value of 053x. EDX bit [0] contains a "1" indicating that an FPU is on chip.

```

switch (EAX)
{
  case (0):
      EAX := 1
      EBX := 69 72 79 43/* 'i' 'r' 'y' 'C' */
      EDX := 73 6e 49 78/* 's' 'n' 'l' 'x' */
      ECX := 64 61 65 74/* 'd' 'a' 'e' 't' */
      break

  case (1):
      EAX[7:0] := 3xh
      EAX[15:8] := 05h
      EDX[0] := 1 /* 1=FPU Built In,0=No FPU */
      break

  default:
      EAX, EBX, ECX, EDX : Undefined
}

```

Figure 2-1. Information Returned by the CPUID Instruction

2.5 EDX Value Following Reset

Some CPU detection algorithms may use the value of the CPU's EDX register following reset. The ST6x86's EDX register contains the data shown below following a reset initiated using the RESET pin:

EDX[31:16] = undefined

EDX[15:8] = 05h

EDX[7:0] = 3x

The value in EDX does not identify the vendor of the CPU. Therefore, EDX alone cannot be used to determine if a SGS-THOMSON CPU is present. However, BIOS should preserve the contents of EDX so that applications can use the EDX value when performing a user-defined shutdown (e.g. a reset performed with data 0Ah in the Shutdown Status byte (Index 0Fh) of the CMOS RAM Map).

3.0 ST6x86 Configuration Register Index Assignments

On-chip configuration registers are used to control the on-chip cache, system management mode and other ST6x86 unique features.

3.1 Accessing a Configuration Register

Access to the configuration registers is achieved by writing the index of the register to I/O port 22h. I/O port 23h is then used for data transfer. Each I/O port 23h data transfer must be preceded by an I/O port 22h register index selection, otherwise the second and later I/O port 23h operations are directed off-chip and produce external I/O cycles. Reads of I/O port 22h are always directed off-chip. Appendix D contains example code for accessing the ST6x86 configuration registers.

3.2 ST6x86 Configuration Register Index Assignments

Table 3-1 lists the ST6x86 configuration register index assignments. After reset, configuration registers with indexes C0-CFh and FC-FFh are accessible. In order to prevent potential conflicts with other devices which may use ports 22 and 23h to access their registers, the remaining registers (indexes 00-BFh, D0-FBh) are accessible only if the MAPEN(3-0) bits in CCR3 are set to 1h. With MAPEN(3-0) set to 1h any access to an index in the 00-FFh range does not create external I/O bus cycles. Registers with indexes C0-CFh, FC-FFh are accessible regardless of the state of the MAPEN bits. If the register index number is outside the C0-CFh or FC-FFh ranges, and MAPEN is set to 0h, external I/O bus cycles occur. Table 3-1 lists the MAPEN values required to access each ST6x86 configuration register. The configuration registers are described in more detail in the following sections.

The ST6x86 configuration registers can be grouped into four areas:

- Configuration Control Registers (CCRs)
- Address Region Registers (ARRs)
- Region Control Registers (RCRs)
- Device Identification Registers (DIRs)

CCR bits independently control ST6x86 features. ARRs and RCRs together define regions of memory with specific attributes. DIRs are used for CPU detection as discussed earlier in Chapter 2. All bits in the configuration registers are initialized to zero following reset unless specified otherwise. The appropriate configuration register bit settings vary depending on system design. Recommendations for optimal settings for a typical PC environment are discussed in Chapter 4.

Table 3.1 Configuration Register Index Assignment

Register Index	Register Name	Acronym	Width (BITS)	MAPEN(3-0)
00h-BFh	Reserved	--	--	--
C0h	Configuration Control 0	CCR0	8	x
C1h	Configuration Control 1	CCR1	8	x
C2h	Configuration Control 2	CCR2	8	x
C3h	Configuration Control 3	CCR3	8	x
C4h-C6h	Address Region 0	ARR0	24	x
C7h-C9h	Address Region 1	ARR1	24	x
CAh-CCh	Address Region 2	ARR2	24	x
CDh-CFh	Address Region 3	ARR3	24	x
D0h-D2h	Address Region 4	ARR4	24	1h
D3h-D5h	Address Region 5	ARR5	24	1h
D6h-D8h	Address Region 6	ARR6	24	1h
D9h-DBh	Address Region 7	ARR7	24	1h
DCh	Region Configuration 0	RCR0	8	1h
DDh	Region Configuration 1	RCR1	8	1h
DEh	Region Configuration 2	RCR2	8	1h
DFh	Region Configuration 3	RCR3	8	1h
E0h	Region Configuration 4	RCR4	8	1h
E1h	Region Configuration 5	RCR5	8	1h
E2h	Region Configuration 6	RCR6	8	1h
E3h	Region Configuration 7	RCR7	8	1h
E4h-E7h	Reserved	--	--	--
E8h	Configuration Control 4	CCR4	8	1h
E9h	Configuration Control 5	CCR5	8	1h
EAh-FDh	Reserved	--	--	--
FEh	Device Identification 0	DIR0	8	x
FFh	Device Identification 1	DIR1	8	x

X = Don't Care

3.3 Configuration Control Registers (CCR0-5)

There are six CCRs in the ST6x86 which control the cache, power management and other unique features. The following paragraphs describe the CCRs and associated bit definitions in detail.

3.3.1 Configuration Control Register 0 (CCR0)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	NC1	Reserved

Table 3.2 CCR0 Bit Definitions

Bit Name	Bit No.	Description
NC1	1	If set, designates 640KBytes -1MByte address region as non-cacheable.

3.3.2 Configuration Control Register 1 (CCR1)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SM3	Reserved	Reserved	NO_LOCK	Reserved	SMAC	USE_SMI	Reserved

Table 3.3 CCR1 Bit Definitions

Bit Name	Bit No.	Description
SM3	7	If set, designates Address Region Register 3 for SMM address space.
NO_LOCK	4	If set, all bus cycles are issued with the LOCK# pin negated except page table accesses and interrupt acknowledge cycles. Interrupt acknowledge cycles are executed as locked cycles even though LOCK# is negated. With NO_LOCK set, previously non-cacheable locked cycles are executed as unlocked cycles and therefore, may be cached. This results in higher CPU performance. See the section on Region Configuration Registers (RCR) for more information on eliminating locked CPU bus cycles only in specific address regions.
SMAC	2	If set, any access to addresses within the SMM address space access system management memory instead of main memory. SMI# input is ignored while SMAC is set. Setting SMAC=1 allows access to SMM memory without entering SMM. This is useful for initializing or testing SMM memory.
USE_SMI	1	If set, SMI# and SMIACT# pins are enabled. If clear, SMI# pin is ignored and SMIACT# pin is driven inactive.

3.3.3 Configuration Control Register 2 (CCR2)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
USE_SUSP	Reserved	Reserved	WPR1	SUSP_HLT	LOCK_NW	Reserved	Reserved

Table 3.4 CCR2 Bit Definition

Bit Name	Bit No.	Description
USE_SUSP	7	If set, SUSP# and SUSPA# pins are enabled. If clear, SUSP# pin is ignored and SUSPA# pin floats. These pins should only be enabled if the external system logic (chipset) support them.
WPR1	4	If set, designates that any cacheable accesses in the 640 KBytes-1MByte address region are write-protected. With WPR1=1, any attempted write to this range will not get issued to the external bus.
SUSP_HLT	3	If set, execution of the HLT instruction causes the CPU to enter low power suspend mode. This bit should be used cautiously since the CPU must recognize and service an INTR, NMI or SMI to exit the "HLT initiated" suspend mode.
LOCK_NW	2	If set, the NW bit in CR0 becomes read only and the CPU ignores any writes to this bit

3.3.4 Configuration Control Register 3 (CCR3)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
MAPEN3	MAPEN2	MAPEN1	MAPEN0	Reserved	LINBRST	NMI_EN	SMI_LOCK

Table 3.5 CCR3 Bit Definitions

Bit Name	Bit No.	Description
MAPEN(3-0)	7-4	If set to 0001 binary (1h), all configuration registers are accessible. If clear, only configuration registers with indexes C0-CFh, FEh and FFh are accessible.
LINBRST	2	If set, the ST6x86 will use a linear address sequence when performing burst cycles. If clear, the ST6x86 will use a "1+4" address sequence when performing burst cycles. The "1+4" address sequence is compatible with the Pentium's burst address sequence.
NMI_EN	1	If set, NMI interrupt is recognized while in SMM. This bit should only be set while in SMM, after the appropriate NMI interrupt service routine has been setup.
SMI_LOCK	0	If set, the CPU prevents modification of the following SMM configuration bits, except when operating in SMM: CCR1 USE_SMI, SMAC, SM3 CCR3 NMI_EN ARR3 Starting address and block size. Once set, the SMI_LOCK bit can only be cleared by asserting the RESET pin.

3.3.5 Configuration Control Register 4 (CCR4)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CPUIDEN	Reserved	Reserved	DTE_EN	Reserved	IORT(2-0)		

Table 3.6 CCR4 Bit Definitions

Bit Name	Bit No.	Description
CPUIDEN	7	If set, bit 21 of the EFLAG register is write/readable and the CPUID instruction will execute normally. If clear, bit 21 of the EFLAG register is not write/readable and the CPUID instruction is an invalid opcode.
DTE_EN	4	If set, the Directory Table Entry cache is enabled.
IORT(2-0)	2-0	Specifies the minimum number of bus clocks between I/O accesses (I/O recovery time). The delay time is the minimum time from the end of one I/O cycle to the beginning of the next (i.e. BRDY# to ADS# time). 0h= 1 clock 1h= 2 clocks 2h=4 clocks 3h= 8 clocks 4h= 16 clocks 5h= 32 clocks (default value after RESETt) 6h= 64 clocks 7h= no delay

3.3.6 Configuration Control Register 5 (CCR5)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Reserved	ARREN	LBR1	Reserved	Reserved	Reserved	WT_ALLOC

Table 3.7 CCR5 Bit Definitions

Bit Name	Bit No.	Description
ARREN	5	If set, enables all Address Region Registers (ARRs). If clear, disables the ARR registers. If SM3 is set, ARR3 is enabled regardless of the ARREN setting.
LBR1	4	If set, LBA# pin is asserted for all accesses to the 640KBytes - 1MByte address region. See section 4.3 for more information on enabling/disabling LBA# for specific address regions.
WT_ALLOC	0	If set, new cache lines are allocated for both read misses and write misses. If clear, new cache lines are only allocated on read misses.

3.4 Address Region Registers (ARR0-7)

The Address Region Registers (ARRs) are used to define up to eight memory address regions. Each ARR has three 8-bit registers associated with it which define the region starting address and block size. Table 3-6 below shows the general format for each ARR and lists the index assignments for the ARR's starting address and block size.

The region starting address is defined by the upper 12 bits of the physical address. The region size is defined by the BSIZE(3-0) bits as shown in Table 3-7. The BIOS and/or its utilities should allow definition of all ARRs. There is one restriction when defining the address regions using the ARRs. The region starting address must be on a block size boundary. For example, a 128KByte block is allowed to have a starting address of 0KBytes, 128KBytes, 256KBytes, and so on.

Table 3.8 ARR_x Index Assignments

Address Region Register	Starting Address			Region Block Size
	A31-A24 Bits (7-0)	A23-A16 Bits (7-0)	A15-A12 Bits (7-4)	BFSIZE(3-0) Bits (3-0)
ARR0	C4h	C5h	C6h	
ARR1	C7h	C8h	C9h	
ARR2	CAh	CBh	CCh	
ARR3	CDh	CEh	CFh	
ARR4	D0h	D1h	D2h	
ARR5	D3h	D4h	D5h	
ARR6	D6h	D7h	D8h	
ARR7	D9h	DAh	DBh	

Table 3.9 BSIZE(3-0) Bit Definition

BSIZE(3-0)	ARR(0-6) Region Size	ARR7 Region Size
0h	Disabled	Disabled
1h	4 KBytes	256 KBytes
2h	8 KBytes	512 KBytes
3h	16 KBytes	1 MByte
4h	32 KBytes	2 MBytes
5h	64 KBytes	4 MBytes
6h	128 KBytes	8 MBytes
7h	256 KBytes	16 MBytes
8h	512 KBytes	32 MBytes
9h	1 MByte	64 MBytes
Ah	2 MBytes	128 MBytes
Bh	4 MBytes	256 MBytes
Ch	8 MBytes	512 MBytes
Dh	16 MBytes	1 Gbytes
Eh	32 MBytes	2 Gbytes
Fh	4 GBytes	4 GBytes

3.5 Region Control Registers (RCR0-7)

The RCRs are used to define attributes, or characteristics, for each of the regions defined by the ARR. Each ARR has a corresponding RCR with the general format shown below.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Reserved	NLB	WT	WG	WL	WWO	RCD/RCE

Note: RCD is defined for RCR0-RCR6. RCE is defined for RCR7 only.

Table 3.10 RCR Bit Definitions

Bit Name	Bit No.	Description
RCD	0	Applicable to RCR(0-6) only. If set, the address region specified by the corresponding ARR is non-cacheable.
RCE	0	Applicable to RCR7 only. If set, the address region specified by ARR7 is cacheable and implies that address space outside of the region specified by ARR7 is non-cacheable.
WWO	1	If set, weak write ordering is enabled for the corresponding region.
WL	2	If set, weak locking is enabled for the corresponding region.
WG	3	If set, write gathering is enabled for the corresponding region.
WT	4	If set, write through caching is enabled for the corresponding region.
NLB	5	If set, LBA# is negated for the corresponding region.

3.5.1 Detailed Description of RCR Attributes

Region Cache Disable (RCD)

Setting RCD=1 defines the corresponding address region as non-cacheable. RCD prevents caching of any access within the specified region. Additionally, RCD implies that high performance features are disabled for accesses within the specified address region. Bus cycles issued to memory addresses within the specified region are single cycles with the CACHE# pin negated. If KEN# is asserted for a memory access within a region defined non-cacheable by RCD, the access is not cached.

Region Cache Enable (RCE)

Setting RCE=1 defines the corresponding address region as cacheable. RCE is applicable to ARR7 only. RCE in combination with ARR7, is intended to define the Main Memory Region. All memory outside ARR7 is non-cacheable when RCE is set. This is intended to define all unused memory space as non-cacheable. If KEN# is negated for an access within a region defined cacheable by RCE, the access is not cached.

Weak Write Ordering (WWO)

Setting WWO=1 enables weak write ordering for the corresponding address region. Weak Write Ordering allows the ST6x86 to retire writes out of sequence to the internal cache only. External write cycles always occur in sequence (strongly ordered). WWO is only applicable to memory regions that have been cached and designated as write-back. WWO should never be enabled for memory mapped I/O.

Weak Locking (WL)

Setting WL=1 enables weak locking for the corresponding address region. With WL enabled, all bus cycles are issued with the LOCK# pin negated except for page table accesses and interrupt acknowledge cycles. WL negates bus locking so that previously non-cacheable cycles can be cached. Typically, XCHG instructions, instructions preceded by the LOCK prefix, and descriptor table accesses are locked cycles. Setting WL allows the data for these cycles to be cached.

Weak Locking (WL) implements the same function as NO_LOCK except that NO_LOCK is a global enable. The NO_LOCK bit of CCR1 enables weak locking for the entire address space, whereas the WL bit enables weak locking only for specific address regions.

Write Gathering (WG)

Setting WG=1 enables write gathering for the corresponding address region. With WG enabled, multiple byte, word or dword writes to sequential addresses that would normally occur as individual write cycles are combined and issued as a single write cycle. WG improves bus utilization and should be used for memory regions that are not sensitive to the "gathering". WG can be enabled for both cacheable and non-cacheable regions.

Write Through (WT)

Setting WT=1 defines the corresponding address region as write-through instead of write-back. Any system ROM that is allowed to be cached by the processor should be defined as write-through.

LBA# Not Asserted (NLB)

Setting NLB=1 prevents the ST6x86 from asserting the Local Bus Access (LBA#) output pin for accesses to that address region. The RCR regions in combination with the LBA# pin can be used to define local bus address regions. The LBA# signal can then be used by external hardware as an indication that accesses are occurring to the local bus.

3.5.2 Attributes for Accesses Outside Defined Regions

If an address is accessed and it is not in the region defined by the ARR_s and ARR₇ is defined with RCE=1, the following conditions apply:

- The memory access is not cached regardless of the state of KEN#.
- The LBA# pin is asserted.
- Writes are not gathered.
- Strong locking occurs.
- Strong write ordering occurs.

3.5.3 Attributes for Accesses in Overlapped Regions

If two defined address regions overlap (including NC1 and LBR1) and conflicting attributes are specified, the following attributes take precedence:

- The LBA# pin is asserted.
- Write-back is disabled.
- Writes are not gathered.
- Strong locking occurs.
- Strong write ordering occurs.
- The overlapping regions are non-cacheable.

Example 1: Overlapping Regions with Conflicting Cacheability

Since the CCR0 bit NC1 affects cacheability, a potential exists for conflict with the ARR7 main memory region which also affects cacheability. This overlap in address regions with conflicting cacheability is a typical configuration for a PC environment. In this case, NC1 takes precedence over the ARR7/RCE setting because non-cacheability always takes precedence. For example, for the following settings:

- NC1=1
- ARR7 = 0-16 Mbytes
- RCR7 bit RCE = 1,

The ST6x86 cache accesses are shown in Table 3-11.

Table 3.11 Cacheability for Example 1

Address Region	Cacheable	Comments
0 to 640 KBytes	Yes	ARR7/RCE setting.
640 KBytes- 1 MByte	No	NC1 takes precedence over ARR7/RCE setting.
1 MByte - 16 MBytes	Yes	ARR7/RCE setting.
16 MBytes - 4 GBytes	No	Default setting.

Example 2: Overlapping Regions with Conflicting Local Bus Designations

Since the CCR5 bit LBR1 affects LBA# assertion, a potential exists for conflict with the RCR NLB bit, which also affects LBA# assertion. Preferably, regions/bits are defined such that there are no conflicting regions. However, in cases where there is a region overlap the LBR1 bit takes precedence over NLB. For example, for the following settings:

- LBR1=1
- ARR0 = 0-16 Mbytes
- RCR0 NLB=1,

The ST6x86 LBA# pin's behaviour is shown in Table 3-12.

Table 3.12 LBA# Behaviour for Example 2

Address Region	LBA# Behaviour	Comments
0 to 640 KBytes	Negated	ARR0/NLB0 setting.
640 KBytes- 1 MByte	Asserted	LBR1 takes precedence over ARR0/NLB0 setting.
1 MByte - 16 MBytes	Negated	ARR0/NLB0 setting.
16 MBytes - 4 GBytes	Asserted	Default setting.

3.5.4 Attributes for Accesses with Conflicting Signal Pin Inputs

The characteristics of the regions defined by the ARR and the RCR may also conflict with indications by hardware signals (i.e., KEN#, WB/WT#). The following paragraphs describe how conflicts between register settings and hardware indicators are resolved.

Non-cacheable Regions and KEN#

Regions which have been defined as non-cacheable (RCD=1) by the ARR and RCR may conflict with the assertion of the KEN# input. If KEN# is asserted for an access to a region defined as non-cacheable, the access is not cached. Regions defined as non-cacheable by the ARR and RCR take precedence over KEN#. The NC1 bit also takes precedence over the KEN# pin. If NC1 is set, any access to the 640k-1 Mbyte address region with KEN# asserted is not cached.

Write-through Regions and WB/WT#

Regions which have been defined as write-through (WT=1) may conflict with the state of the WB/WT# input to the ST6x86. Regions defined as write-through by the ARR and RCR remain write-through even if WB/WT# is asserted during accesses to these regions. The WT bit in the RCR takes precedence over the state of the WB/WT# pin in cases of conflict.

4.0 Recommended ST6x86 Configuration Register Settings

4.1 PC Memory Model

Table 4.1 PC Memory Model

Address Space	Address Range	Cacheable	Weak Writes	Weak Locks	Write Gathered	Write-through	NOTES
DOS Area	0-9FFFFh	Yes	Yes	No	Yes	No	
Video Buffer	A0000-BFFFFh	No	No	No	Yes	No	Note 1
Video ROM	C0000-C7FFFh	Yes	No	No	No	Yes	Note 2
Expansion Card/ROM Area	C8000h-DFFFFh	No	No	No	No	No	
System ROM	E0000h-FFFFFh	Yes	No	No	No	Yes	Note 2
Extended Memory	100000h-Top of Main Memory	Yes	Yes	No	Yes	No	
Unused/PCI MMIO	Top of Main Memory-FFFFFFFh	No	No	No	No	No	Note 3

Table 4-1 defines the allowable attributes for a typical PC memory model. Actual recommended configuration register settings for an example PC system are listed in Appendix F.

Notes:

1. Video Buffer Area

A non-cacheable region must be used to enforce strong cycle ordering in this area and to prevent caching of video RAM. The video ram area is sensitive to bus cycle ordering. The VGA controller can perform logical operations which depend on strong cycle ordering (found in Windows 3.1 code). To guarantee that the ST6x86 performs strong cycle ordering, a non-cacheable area must be established to cover the video ram area.

Video performance is greatly enhanced by gathering writes to Video RAM. For example, video performance benchmarks have been found to use REP STOSW instructions that would normally execute as a series of sequential 16-bit write cycles. With WG enabled, groups of four 16-bit write cycles are reduced to a single 64-bit write cycle.

2. Video ROM and System ROM

Caching of the Video and System ROM areas is permitted, but is normally non-cacheable because NC1 is set. If these areas are cached, they must be cached as write-through regions. Benchmarking on ST6x86 systems in a Windows environment has shown no benefit to caching these ROM areas. Therefore, it is recommended that these areas be set as non-cacheable using the NC1 bit in CCR0.

3. Top of Main Memory-FFFFFFFh (Unused/PCI Memory Space)

Unused/PCI Memory Space immediately above physical main memory must be defined as non-cacheable to ensure proper operation of memory sizing software routines and to guarantee strong cycle ordering. Memory discovery routines must occur with cache disabled to prevent read sourcing from the write buffers. Also, PCI memory mapped I/O cards that may exist in this address region may contain control registers or FIFOs that depend on strong cycle ordering.

The appropriate non-cacheable region must be established using ARR7. For example, if 32 Mbytes (0000000-1FFFFFFFh) are installed in the system, a non-cacheable region must begin at the 32 Mbyte boundary (2000000h) and extend through the top of the address space (FFFFFFFh). This is accomplished by using ARR7 (Base = 0000 0000h, BSize=32Mbytes) in combination with RCE=1.

4.2 General Recommendations

4.2.1 Main Memory

Memory discovery routines should always be executed with the L1 cache disabled. By default, L1 caching is globally disabled following reset because the CD bit in Control Register 0 (CR0) is set. Always ensure the L1 cache is disabled by setting the CD bit in CR0 or by programming an ARR to “4 Gbyte cache disabled” before executing the memory discovery routine. Once BIOS completes memory discovery, ARR7 should be programmed with a base address of 0000000h and with a “Size” equal to the amount of main memory that was detected.

The intent of ARR7 is to define a cacheable region for main memory and simultaneously define unused/PCI space as non-cacheable. More restrictive regions are intended to overlay the 640k to 1Mbyte area. Failure to program ARR7 with the correct amount of main memory can result in the following:

- Incorrect memory sizing by the operating system eventually resulting in failure,
- PCI devices not working correctly or causing system hangs,
- Low performance if ARR7 is programmed with a smaller size than the actual amount of memory.

If the granularity selection in ARR7 does not accommodate the exact size of main memory, unused ARRs can be used to fill-in as non-cacheable regions. All unused/PCI memory space must always be set as non-cacheable.

4.2.2 I/O Recovery Time (IORT)

Back-to-back I/O writes followed by I/O reads may occur too quickly for a peripheral to respond correctly. Historically, programmers have inserted several “JMP \$+2” instructions in the hope that code fetches on the bus would create sufficient recovery time. The ST6x86's Branch Target Buffer (BTB) typically eliminates these external code fetches, thus the previous method of guaranteeing I/O recovery no longer applies. For the ST6x86, one approach to dealing with this issue is to insert I/O write cycles to a dummy port. I/O write cycles in the form “out imm,reg” are easily implemented as shown below:

OLD IORT	NEW IORT
out 21h,al	out 21h,al
jmp \$+2	out 80h,al
jmp \$+2	out 80h,al
jmp \$+2	out 80h,al
in al,21h	in al,21h

The ST6x86 incorporates an alternative method for implementing I/O recovery time using user selectable delay settings. See the section on ST6x86 IORT settings below.

4.2.3 BIOS Creation Utilities

BIOS creation utilities or setup screens must have the capability to easily define and modify the contents of the ST6x86 configuration registers. This allows OEMs and integrators to easily configure these register settings with the values appropriate for their system design.

4.2.4 Branch Target Buffer (BTB)

In the default state, the ST6x86 BTB stores target addresses for near change-of-flow instructions (COFs) only. To enhance the performance of the ST6x86, the BTB should be configured to store target addresses for both near and far COFs. This feature is controlled through reserved configuration and test registers. Sample code used to enable this feature is listed in Appendix G.

4.3 Recommended Bit Settings

4.3.1 NC1

The NC1 bit in CCR0 is a predefined non-cacheable region from 640k to 1MByte. The 640k to 1MByte region should be non-cacheable to prevent L1 caching of expansion cards using memory mapped i/o (MMIO). Setting NC1 also implies that the video BIOS and system BIOS are non-cacheable. Experiments with both the ST6x86 and Pentium show that modern operating systems and benchmark applications (such as WinStone95) are unchanged when caching/non-caching system and video BIOS.

Suggested setting

NC1= 1

4.3.2 NO_LOCK

NO_LOCK enables weak locking for the entire address space. NO_LOCK may cause failures for software that requires locked cycles in order to operate correctly.

Suggested setting

NO_LOCK = 0

4.3.3 LOCK_NW

Once set, LOCK_NW prohibits software from changing the NW bit in CR0. Since the definition of the NW bit is the same for both the ST6x86 and the Pentium, it is not necessary to set this bit.

Suggested setting

LOCK_NW = 0

4.3.4 WPR1

WPR1 forces cacheable accesses in the 640k to 1MByte address region to be write-protected. If NC1 is set (recommended setting), all caching is disabled from 640k to 1MByte and WPR1 is not required. However, if ROM areas within the 640k-1MByte address region are cached, WPR1 should be set to protect against errant self-modifying code.

Suggested setting

WPR1 = 0 unless ROM areas are cached

4.3.5 LINBRST

Linear Burst (LINBRST) allows for an alternate address sequence for burst cycles. The system logic and motherboard design must also support this feature in order for the ST6x86 to function properly with this bit enabled. Linear Burst provides higher performance than the default "1+4" burst sequence, but should only be enabled if the system is designed to support it.

If the system does support linear burst, BIOS should enable this feature in both the system logic and the ST6x86 prior to enabling the L1 cache.

Suggested setting

LINBRST = 0 unless linear burst supported by the system

4.3.6 MAPEN

When set to 1h, the MAPEN bits allow access to all ST6x86 configuration registers including indexes outside the C0h-CFh and FCh-FFh ranges. MAPEN should be set to 1h only to access specific configuration registers and then should be cleared after the access is complete.

Suggested setting

MAPEN(3-0)= 0 except for specific configuration register accesses

4.3.7 IORT

I/O recovery time specifies the minimum number of bus clocks between I/O accesses for the CPU's bus controller. The system logic typically also has a built-in method to select the amount of I/O recovery time. It is preferred to configure the system logic with the I/O recovery time setting and set the CPU for a minimum I/O recovery time delay.

Suggested setting

IORT(2-0) = 7

4.3.8 DTE_EN

DTE_EN allows Directory Table Entries (DTE) to be cached on the ST6x86. This provides a performance improvement for some applications that access and modify the page tables frequently.

Suggested setting

DTE_EN = 1

4.3.9 CPUIDEN

When set, the CPUIDEN bit enables the CPUID instruction and CPUID detection. By default, the CPUID instruction is disabled (CPUIDEN=0). In the default state, the CPUID opcode 0FA2 causes an invalid opcode exception. Additionally, the CPUID bit in the EFLAGS register cannot be modified by software. When enabled the CPUID opcode is enabled and the CPUID bit in the EFLAGS can be modified. The CPUID instruction can then be called to inspect the type of CPU present.

CPUID is disabled by default to guarantee compatibility with popular software that improperly uses CPUID and misidentifies the ST6x86. Misidentification of the processor can eventually result in runtime failures.

Suggested setting

CPUIDEN = 0

4.3.10 WT_ALLOC

Write Allocate (WT_ALLOC) allows L1 cache write misses to cause a cache line allocation. This feature improves the L1 cache hit rate resulting in higher performance especially for Windows applications.

Suggested setting

WT_ALLOC= 1

4.3.11 LBR1

LBR1 when set causes the LBA# (Local Bus Access) pin to be asserted for accesses between 640k to 1MByte. This feature is not used for most systems.

Suggested setting

LBR1= 0

4.3.12 ARREN

The ARREN bit enables/disables all eight ARR. When ARREN is cleared (default), the ARRs can be safely programmed. Most systems will need to use at least one address region register (ARR). Therefore, ARREN should always be set after the ARRs and RCRs have been initialized.

Suggested setting

ARREN = 1 after initializing ARR0-ARR7, RCR0-RCR7

4.3.13 ARR7 and RCR7

Address Region 7 (ARR7) defines the Main Memory Region (MMR). This region specifies the amount of cacheable main memory and its attributes. Once BIOS completes memory discovery, ARR7 should be programmed with a base address of 0000000h and with a "Size" equal to the amount of main memory installed in the system. Memory accesses outside this region are defined as non-cacheable to ensure compatibility with PCI devices.

Suggested settings

ARR7 Base Addr= 0000 0000h

ARR7 Block Size= amount of main memory

RCR7 RCE= 1

RCR7 WWO= 1

RCR7 WL= 0

RCR7 WG= 1

RCR7 WT= 0

RCR7 NLB= 0

If the granularity selection in ARR7 does not accommodate the exact size of main memory, unused ARRs can be used to fill-in as non-cacheable regions (RCD = 1) as shown in Table 4-2. All unused/PCI memory space must always be set as non-cacheable

Table 4.2 ARR Settings for Various Main Memory Sizes

Mem	ARR7		ARR6		ARR5		ARR4	
	Base (hex)	Size (MB)	Base (hex)	Size (MB)	Base (hex)	Size (MB)	Base (hex)	Size (MB)
8	0	8						
16	0	16						
24	0	32	0180 0000	8				
32	0	32						
40	0	64	0300 0000	16	0280 0000	8		
48	0	64	0300 0000	16				
64	0	64						
72	0	128	0600 0000	32	0500 0000	16	0480 0000	8
80	0	128	0600 0000	32	0500 0000	16		
96	0	128	0600 0000	32				
128	0	128						
160	0	256	0E00 0000	32	0C00 0000	32	0A00 0000	32
192	0	256	0E00 0000	32	0C00 0000	32		
256	0	256						

4.3.14 SMM Features

The ST6x86 supports SMM mode through the use of the SMI# and SMIACT# pins, and a dedicated memory region for the SMM address space. SMM features must be enabled prior to servicing any SMI interrupts. The following paragraphs describe each of the SMM features and recommended settings.

USE_SMI

Prior to servicing SMI interrupts, SMM-capable systems must enable the SMM pins by setting USE_SMI=1. The SMM hardware pins (SMI# and SMIACT#) are disabled by default.

SMAC

If set, any access to addresses within the SMM address space accesses SMM memory instead of main memory. Setting SMAC allows access to the SMM memory without servicing an SMI. Additionally, SMAC allows use of the SMINT instruction (software SMI). This bit may be enabled to initialize or test SMM memory but should be cleared for normal operation.

SM3 and ARR3

Address Region Register 3 (ARR3) can be used to define the System Management Address Region (SMAR). Systems that use SMM features must use ARR3 to establish a base and limit for the SMM address space.

Only ARR3 can be used to establish the SMM region.

Typically, SMAR overlaps normal address space. RCR3 defines the attributes for both the SMM address region AND the normal address space. If SMAR overlaps main memory, write gathering should be enabled for ARR3. If SMAR overlaps video memory, ARR3 should be set as non-cacheable and write gathering should be enabled.

NMI_EN

The NMI_EN bit allows NMI interrupts to occur within an SMI service routine. If this feature is enabled, the SMI service routine must guarantee that the IDT is initialized properly to allow the NMI to be serviced. Most systems do not require this feature.

SMI_LOCK

Once the SMM features are initialized in the configuration registers, they can be permanently locked using the SMI_LOCK bit. Locking the SMM related bits and registers prevents applications from tampering with these settings. Even if SMM is not implemented, setting SMI_LOCK in combination with SMAC=0 prevents software SMIs from occurring.

Once SMI_LOCK is set, it can only be cleared by a processor RESET. Consequently, setting SMI_LOCK makes system/BIOS/SMM debugging difficult. To alleviate this problem, SMI_LOCK must be implemented as a user selectable "Secure SMI (enable/disable)" feature in CMOS setup. If SMI_LOCK is not user selectable, it is recommended that SMI_LOCK = 0 to facilitate system debug.

Suggested settings for systems not using SMM

USE_SMI = 0

SMAC = 0

SM3 = 0

ARR3 = may be used as normal address region register

SMI_LOCK = 0

NMI_EN = 0

Suggested settings for systems using SMM

USE_SMI = 1

SMAC = 0

SM3 = 1

ARR3 Base Addr = as required

ARR3 Block Size= as required

SMI_LOCK = 0

NMI_EN = 0

4.3.15 Power Management Features

SUSP_HALT

Suspend on Halt (SUSP_HLT) permits the CPU to enter a low power suspend mode when a HLT instruction is executed. Although this provides some power management capability, it is not optimal.

Suggested setting

SUSP_HALT = 0

USE_SUSP

In addition to the HLT instruction, low power suspend mode may be activated using the SUSP# input pin. In response to the SUSP# input, the SUSPA# output indicates when the ST6x86 has entered low power suspend mode. Systems that support the ST6x86's low power suspend feature via the hardware pins must set USE_SUSP to enable these pins.

Suggested setting

USE_SUSP = 0 unless hardware suspend pins supported

5.0 Programming Model Differences

5.1 Instruction Set

The ST6x86 supports the 486 instruction set. Pentium extensions for virtual mode, additional debug capability, and internal counters are not supported.

5.2 Configuring Internal ST6x86 Features

The ST6x86 supports configuring internal features through I/O ports. The ST6x86 does not support configuring internal features through the WRMSR and RDMSR instructions which are treated as invalid opcodes.

5.3 INVD and WBINVD Instructions

The INVD and WBINVD instructions are used to invalidate the contents of the internal and external caches. The WBINVD instruction first writes back any modified lines in the cache and then invalidates the contents. It ensures that cache coherency with system memory is maintained regardless of the cache operating mode. Following invalidation of the internal cache, the CPU generates special bus cycles to indicate that external caches should also write back modified data and invalidate their contents.

On the ST6x86, the INVD functions identically to the WBINVD instruction. The ST6x86 always writes all modified internal cache data to external memory prior to invalidating the internal cache contents. In contrast, the Pentium invalidates the contents of its internal caches without writing back the "dirty" data to system memory. The Pentium behavior can potentially result in a data incoherency between the CPU's internal cache and system memory.

5.4 Control Register 0 (CR0) CD and NW Bits

The CPU's CR0 register contains, among other things, the CD and NW which are used to control the on-chip cache. CR0, like the other system level registers, is only accessible to programs running at the highest privilege level. Table 5.1 lists the cache operating modes for the possible states of the CD and NW bits.

The CD and NW bits are set to one (cache disabled) after reset. For highest performance the cache should be enabled in write-back mode by clearing the CD and NW bits to 0. Sample code for enabling the cache is listed in Appendix E. To completely disable the cache, it is recommended that CD and NW be set to 1 followed by execution of the WBINVD instruction. The ST6x86 cache always accepts invalidation cycles even when the cache is disabled. Setting CD=0 and NW=1 causes a General Protection fault on the Pentium, but is allowed on the ST6x86 to globally enable write-through caching.

Table 5.1 Cache Operating Mode

CD	NW	OPERATING MODES
1	1	<p>Cache disabled.</p> <p>Read hits access the cache.</p> <p>Read misses do not cause line fills.</p> <p>Write hits update the cache and system memory.</p> <p>Write hits change exclusive lines to modified.</p> <p>Shared lines remain shared after write hit.</p> <p>Write misses access memory.</p> <p>Inquiry and invalidation cycles are allowed.</p> <p>System memory coherency maintained.</p>
1	0	<p>Cache disabled.</p> <p>Read hits access the cache.</p> <p>Read misses do not cause line fills.</p> <p>Write hits update the cache.</p> <p>Only write hits to shared lines and write misses update system memory.</p> <p>Write misses access memory.</p> <p>Inquiry and invalidation cycles are allowed.</p> <p>System memory coherency maintained.</p>
0	1	<p>Cache enabled in Write-through mode.</p> <p>Read hits access the cache.</p> <p>Read misses may cause line fills.</p> <p>Write hits update the cache and system memory.</p> <p>Write misses access memory.</p> <p>Inquiry and invalidation cycles are allowed.</p> <p>System memory coherency maintained.</p>
0	0	<p>Cache enabled in Write-back mode.</p> <p>Read hits access the cache.</p> <p>Read misses may cause line fills.</p> <p>Write hits update the cache.</p> <p>Write misses access memory and may cause line fills if write allocation is enabled.</p> <p>Inquiry and invalidation cycles are allowed.</p> <p>System memory coherency maintained.</p>

6.0 Appendix

6.1 Appendix A - Sample Code: Detecting a SGS-THOMSON CPU

```

assume cs:_TEXT
public _issgs
_TEXT segment byte public 'CODE'
*****
;
;   Function:   int issgs ()
;
;
;   Purpose:    Determine if SGS-THOMSON CPU is present.
;   Technique:  SGS-THOMSON CPUs do not change flags where flags
;               change in an undefined manner on other CPUs
;
;   Inputs:     none
;   Output:     ax = 1 SGS-THOMSON present, 0 if not
*****
;

_issgsproc    near
               .386
               xor    ax, ax           ; clear ax
               sahf   ; clear flags, bit 1 always=1 in flags
               mov    ax, 5
               mov    bx, 2
               div    bl           ; operation that doesn't change flags
               lahf   ; get flags
               cmp    ah, 2        ; check for change in flags
               jne    not_sgs      ; flags changed, therefore NOT SGS
               mov    ax, 1        ; TRUE SGS CPU
               jmp    done

not_sgs:
               mov    ax, 0        ; FALSE NON-SGS CPU

done:
               ret

_issgs    endp
_TEXT ends
end

```

Figure 1

6.2 Appendix B - Sample Code: Determining CPU MHz

```

assume cs:_TEXT
public _cpu_speed
_TEXT segment para public 'CODE'

comment~
*****
Function:  unsigned long _cpu_speed( unsigned int )
           "C" style caller
Purpose:   calculate elapsed time req'd to complete a loop of IDIVs

Technique: Use the PC's high resolution timer/counter chip (8254)
           to measure elapsed time of a software loop consisting
           of the IDIV and LOOP instruction.
Definitions: The 8254 receives a 1.19318MHz clock (0.8380966 usec).
            One "tick" is equal to one rising clock edge applied
            to the 8254 clock input.
Inputs:    ax = no. of loops for cpu_speed_loop
Returns:   ax = no. of 1.19318MHz clk ticks req'd to complete a loop
           dx = state of 8254 out pin

PortB      EQU      061h
Timer_Ctrl_Reg  EQU      043h
Timer_2_Data  EQU      042h
stk$dx      EQU      10           ;dx register offset
stk$ax      EQU      14           ;dx register offset
stack$ax    EQU      [bp]+stk$ax
stack$dx    EQU      [bp]+stk$dx
Loop_Count  EQU      [bp+16]+4

.386p

_cpu_speed  proc near
            pushf                ;save interrupt flag
            pusha                ;pushes 16 bytes on stack
            mov     bp,sp        ;init base ptr

```

continued

Figure 2

```

;-----initialize the 8254 counter to "0", known value
mov     al,0b0h
out     Timer_Ctrl_Reg, al    ;control word to set channel 2 count
out     80h,al               ;I/O recovery time
mov     al,0ffh
out     Timer_2_Data, al     ;init count to 0, lsb
out     80h,al               ;I/O recovery time
out     Timer_2_Data, al     ;init count to 0, msb
;-----get the number of loops from the caller's stack
mov     cx,Loop_Count       ;loop count
;-----load dividend & divisor, clk count for IDIV depend on operands!
xor     edx,edx              ;dividend EDX:EAX
xor     eax,eax
mov     ebx,1                ;divisor
;-----enable the timer/counter's clock. Begin timed portion of test!
xchg   ax, di                ;save ax for moment
or     al, 1
out    PortB, al             ;enable timer/counter 2 clk
xchg   ax, di                ;restore ax
;-----this is the core loop.
ALIGN 16
cpu_speed_loop:
    idiv ebx
    idiv ebx
    idiv ebx
    idiv ebx
    idiv ebx
    loop cpu_speed_loop
;-----disable the timer/counter's clk. End timed portion of test!
mov    ax, di
and    al, 0FEH
out    PortB, al

```

continued

Figure 2

```

;-----send latch status command to the timer/counter
    mov     al, 0c8h                ;latch status and count
    out    Timer_Ctrl_Reg, al
    out    80h,al                  ;I/O recovery time
;-----read status byte, and count value "ticks" from the timer/cntr
    in     al, Timer_2_Data         ;read status
    out    80h,al                  ;I/O recovery time
    mov    dl, al
    and    dx, 080h
    shr    dx, 7
    in     al, Timer_2_Data         ;read LSB
    out    80h,al                  ;I/O recovery time
    mov    bl, al
    in     al, Timer_2_Data         ;read MSB
    out    80h,al                  ;I/O recovery time
    mov    bh, al
    not    bx                       ;invert count
;-----send command to clear the timer/counter
    mov    al, 0b6h
    out    Timer_Ctrl_Reg, al      ;clear channel 2 count
    out    80h,al                  ;I/O recovery time
    xor    al, al
    out    Timer_2_Data, al        ;set count to 0, lsb
    out    80h,al                  ;I/O recovery time
    out    Timer_2_Data, al        ;set count to 0, msb
;-----put return values on the stack for the caller
    mov    [bp+stk$ax], bx
    mov    [bp+stk$dx], dx
    popa
    popf                             ;restores interrupt flag
    ret
_cpu_speed      endp
.8086
_TEXT          ENDS
END

```

Figure 2

6.3 Appendix C - Example CPU Type and Frequency Detection Program

/

```

* ****
function:  main()                WCP 8/22/95
Purpose:   a driver program to demonstrate:
           CPU detection
           CPU core frequency in Mhz.
Returns:   0 if successful

Required source code modules
ST6x86_stat.c      main() module (this file)
id.asm             cpu identification code
clock.asm          cpu timing loop

Compile and Link instructions for Borland C++ or equivalent:
bcc ST6x86_stat.c id.asm clock.asm
****/

/* include directives */
#include <stdio.h>
/* constants */
#define TTPS      1193182        //high speed Timer Ticks per second in Mhz
#define MHZ       1000000       //number of clocks in 1 Mhz
#define LOOP_COUNT 0x2000      //core loop iterations
#define RUNS      10           //number of runs to average
#define DIVS      5            //# of IDIV instructions in the core loop
#define ST6x86_IDIV_CLKS 17    //known clock counts for ST6x86
#define ST6x86_LOOP_CLKS 1
#define P54_IDIV_CLKS 46       //known clock counts for P54
#define P54_LOOP_CLKS 7

/* prototypes */
unsigned int  issgs ( void );           //detects SGS cpu
unsigned long cpu_speed( unsigned int ); //core timing loop

main(){

/* declarations */
unsigned char uc_sgs_cpu = 0;          //SGS cpu? 0=no, 1=yes
unsigned int  i_runs = 0;              //number of runs to avg
unsigned int  ui_idiv, ui_loop = 0;    //instruction clk counts

continued

```

Figure 3

```

    unsigned long ul_tt_cnt, ul_tt_sum = 0;           //timer tick counts, sum
    unsigned int  ui_core_loop_cntr = LOOP_COUNT;    //core loop iterations
    float         f_mtt = 0;                        //measured timer ticks
    float         f_total_core_clks = 0;            //calculated core clocks
    float         f_total_time = 0;                 //measured time
    float         f_mhz = 0;                        //mhz

/* ***** determine if SGS CPU is present ***** */
//detect if SGS CPU is present
    uc_sgs_cpu = issgs();                          //1=sgs, 0=non-sgs

//display a msg
    if(uc_sgs_cpu) printf("\nSGS-THOMSON CPU present! ");
    else printf("\nSGS-THOMSON CPU not present! ");
/* ***** determine CPU Mhz ***** */

//count # of hi speed "timer ticks" to complete several runs of core loop
for (i_runs = 0 ; i_runs < RUNS ; i_runs++) {
    ul_tt_cnt = cpu_speed( ui_core_loop_cntr );
    ul_tt_sum += ul_tt_cnt;                        //sum them all together
} //end for

//compute the avg number of high speed "timer ticks" for the several runs
    f_mtt = ul_tt_sum / RUNS;                      //compute the average

//initialize variables with the "known" clock counts for a ST6x86 or P54
    if(uc_sgs_cpu) ui_loop=ST6x86_LOOP_CLKS; else ui_loop=P54_LOOP_CLKS;
    if(uc_sgs_cpu) ui_idiv=ST6x86_IDIV_CLKS; else ui_idiv=P54_IDIV_CLKS;

//determine the total number of core clocks.(5 idivs are in the core loop)
    f_total_core_clks = (float)ui_core_loop_cntr * (ui_idiv * DIVS + ui_loop);

//the time it took to complete the core loop can be determined by the
//ratio of measured timer ticks(mtt) to timer ticks per second(TTPS).
    f_total_time = f_mtt / TTPS;

//frequency can be found by the ratio of core clks to the total time.
    f_mhz = f_total_core_clks / f_total_time;
    f_mhz = f_mhz / MHZ;                          //convert to Mhz

//display a msg
    printf("The core clock frequency is: %3.1f MHz\n\n",f_mhz);
    return(0);
} // end main

```

Figure 3

6.4 Appendix D- Sample Code : Programming ST6x86 Configuration Registers

6.4.1 Reading/Writing Configuration Registers

```

Sample code for setting NCl=1 in CCR0.
pushf                ;save the if flag
cli;                 ;disable interrupts
mov  al, 0c0h        ;set index for CCR0
out  22h, al;        ;select CCR0 register
in   al, 23h         ;READ current CCR0 valueREAD

mov  ah, al
or   ah, 2h;         ;MODIFY,set NCl bitMODIFY

mov  al, 0c0h        ;set index for CCR0
out  22h, al        ;select CCR0 register
mov  al, ah
out  23h,al         ;WRITE new value to CCR0WRITE
popf                 ;restore if flag

```

Figure 4

6.4.2 Setting MAPEN

```

Sample code for setting MAPEN=1 in CCR3 to allow access to all of the
configuration registers.

pushf                ;save the if flag
cli;                 ;disable interrupts
mov  al, 0c3h        ;set index for CCR3
out  22h, al        ;select CCR3 register
in   al, 23h         ;current CCR3 valueREAD

mov  ah, al
and  ah,0Fh          ;clear upper nibble of ah
or   ah, 10h;        ;MODIFY,set MAPEN(3-0)MODIFY

mov  al, 0c3h        ;set index for CCR3
out  22h, al        ;select CCR3 register
mov  al, ah
out  23h,al         ;WRITE new value to CCR3WRITE
popf                 ;restore if flag

```

Figure 5

6.5 Appendix E - Sample Code: Controlling the L1 Cache

6.5.1 Enabling the L1 Cache

```
;reading/writing CR0 is a privileged operation.  
mov  eax, cr0  
and  eax, 09fffffffh      ;clear the CD=0, NW=0 bits to enable write-back  
mov  cr0, eax            ;control register 0 write  
wbinvd                   ;optional, by flushing the L1 cache here it  
                          ;ensures the L1 cache is completely clean
```

Figure 6

6.5.2 Disabling the L1 Cache

```
mov  eax, cr0  
or   eax, 060000000h      ;set the CD=1, NW=1 bits to disable caching  
mov  cr0, eax            ;control register 0 write  
wbinvd
```

Figure 7

Table 6.6 Configuration Register Settings

RCR1	RCD	1	Caching disabled for compatibility. Caching also disabled via NC1.
	WVO	0	
	WL	0	
	WG	0	
	WT	0	
	NLB	0	
ARR3	BASE ADDR	A0000h	SMM address region base address
	BLOCK SIZE	4h	SMM address space = 32 KBytes
RCR3	RCD	1	Caching disabled due to overlap with video buffer. Write gathering enabled due to overlap with video buffer.
	WVO	0	
	WL	0	
	WG	1	
	WT	0	
	NLB	0	
ARR7	BASE ADDR	0h	Main memory base address = 0h.
	BLOCK SIZE	7h	Main memory size = 16 MBytes.
RCR7	RCE	1	Caching, weak write ordering, and write gathering enabled for main memory.
	WVO	1	
	WL	0	
	WG	1	
	WT	0	
	NLB	0	
ARR(2,4-6)	BASE ADDR	0	ARR(2,4-6) disabled (default state).
RCR(2,4-6)	BLOCK SIZE	0	RCR(2,4-6) not required due to corresponding ARR(2,4-6) disabled (default state).
	RCD	0	
	WVO	0	
	WL	0	
	WG	0	
	WT	0	
NLB	0		

6.7 Appendix G - Sample Code: Enabling FAR COFs in BTB

```

Below is sample code that enables FAR COFs in the BTB.
;-----First, set MAPEN to allow access to all ST6x86 configuration regs
mov  al, 0C3h          ;READ
out  22h, al
in   al, 23h

mov  ah, al           ;MODIFY
or   ah, 10h
and  ah, 1Fh

mov  al, 0C3h        ;WRITE
out  22h, al
mov  al, ah
out  23h, al

;-----Enable ST6x86 test register opcodes
mov  al, 30h         ;READ debug register (index 30)
out  22h, al
in   al, 23h

mov  ah, al           ;MODIFY enable tr opcodes
or   ah, (1 SHL 6)

mov  al, 30h         ;WRITE debug reg (index 30h)
out  22h, al
mov  al, ah
out  23h, al

;-----Enable FAR COF hits (index 5, bit 1)
mov  ebx,28h         ;select index 5
movtr _tr1,_ebx
db   0Fh,26h,0CBh    ;opcodes for movtr _tr1,_ebx

movtr _eax,_tr2      ;READ test reg index 5
db   0Fh,24h,0D0h    ;opcodes for movtr _eax,_tr2
and  eax,0FFFFFFFDh  ;MODIFY

```

continued

Figure 8

```
movtr _tr2,_eax          ;WRITE new data to test reg 5
db    0Fh,26h,0D0h      ;opcodes for movtr _tr2,_eax

mov    debug_reg_0,eax   ;save value for later

;-----Disable ST6x86 Test Register Opcodes
mov    al, 30h           ;READ debug reg DBR0
out    22h, al
in     al, 23h

mov    ah, al            ;MODIFY
and    ah, 0BFh         ;turn off tr opcodes

mov    al, 30h           ;WRITE
out    22h, al
mov    al, ah
out    23h, al

;-----Restore mapen to default state
mov    al, 0C3h         ;READ
out    22h, al
in     al, 23h

mov    ah, al            ;MODIFY
and    ah, 0Fh         ;turn off mapen

mov    al, 0C3h         ;WRITE
out    22h, al
mov    al, ah
out    23h, al
```

Figure 8

6.8 Appendix H - Sample Code: Detecting L2 Cache Burst Mode

```

*****
Purpose:   This example program detects if the Linear Burst mode is supported.
Method:    There are 3 components (CPU, chipset, SPBSRAM) that must agree on the
           burst order. The CPU and chipset burst order can be determined by inspecting each
           devices' internal configuration registers. The SPBSRAM devices must be interrogated
           by a software algorithm (below) to determine if "linear burst mode" is enabled/
           supported correctly.
Algorithm: If the CPU and chipset are programmed for linear burst mode and a known data
           pattern exists in memory, then the burst mode of the SPBSRAMs can be
           determined by performing a cache line burst and then inspecting the data pattern.
Application: In this example, the SIS5511 chipset is used with a SGS-THOMSON STST6x86
            CPU.
Environment: This program is a REAL mode DOS program to serve as an example. This
            example algorithm should be ported to BIOS.
Warnings:   For simplicity, this program does not check to see which CPU or chipset is
            present nor does it check to see if the CPU is in the REAL mode before
            executing protected instructions. Also, this program blindly overwrites data in the
            8000h segment of memory.
*****
;version m510                      ;remove comment for TASM
DOSSEG
.MODEL SMALL
.DATA

Msg_1db      0dh,0ah
db          'ISLINBUR.EXE checks if L2 SRAMs are in Linear Burst Mode or'
db          0dh,0ah
db          'Toggle Burst mode for the SIS5511 chipset and the STST6x86 CPU.'
db          0dh,0ah
db          '$'
Msg_2 db      0dh,0ah
db          'Test complete!'
db          0dh,0ah
db          '$'
Msg_yes      db 0dh,0ah
db          'The L2 SRAMs correctly operate in linear burst mode.'
db          0dh,0ah
db          '$'
Msg_no      db 0dh,0ah
db          'ERROR: The L2 SRAMs incorrectly operate in linear burst mode.'
db          0dh,0ah
db          '$'

```

continued

Figure 9

```

index_port    dw    0CF8h
data_port     dw    0CFCh
pci_index     dd    80000000h

.STACK 100h
.CODE
.STARTUP
.486P

pushf
cli

;-----display a msg using a DOS call
mov    ax,seg Msg_1
mov    ds,ax
mov    dx,offset Msg_1      ;set msg_1 start
mov    ah,9h                ;print string function
int    21h                  ;DOS int

;-----disable the L1 internal cache
call   cache_off
out    80h,al                ;write to PC diagnostic port

;-----setup a work space in main memory to perform burst mode tests
;and initialize the memory work space with a known pattern
push   ds
mov    ax,8000h              ;choose segment 8000h
mov    ds,ax
mov    al,0001h
mov    byte ptr ds:[0],al    ;init memory locations
inc    al
mov    byte ptr ds:[8h],al
inc    al
mov    byte ptr ds:[10h],al
inc    al
mov    byte ptr ds:[18h],al
pop    ds

;-----enable the SiS5511 chipset's linear burst mode
mov    al,51h                ;al=reg to read
call   r_pci_reg             ;READ al=reg contents
mov    ah,al
or     ah,8                  ;MODIFY set linbrst bit
mov    al,51h
call   w_pci_reg             ;WRITE

;-----enable the CPU's linear burst mode
call   en_linbrst

;-----enable L1 caching
call   cache_on

```

continued

Figure 9

```

;-----burst several cache lines so that address 80000h is in the L2
;cache, but NOT in the L1 cache.
push    ds
mov     ax,8000h                ;choose segment 8000h
mov     ds,ax
mov     al,byte ptr ds:[0h]    ;do a line fill to L2 and L1
mov     al,byte ptr ds:[1000h] ;fill L1 line 1
mov     al,byte ptr ds:[2000h] ;fill L1 line 1
mov     al,byte ptr ds:[3000h] ;fill L1 line 1
mov     al,byte ptr ds:[4000h] ;fill L1 line 1,
;now 80000h exists only in the
;L2 cache (not in L1 anymore!)

;---burst a cache line so that address 80000h will hit the L2 cache SRAMs
mov     al,byte ptr ds:[8h]
;***** Burst Pattern Table *****
;if SRAMs in linear burst mode, then
;L1 will be filled with:
; byte data
; 0 01h
; 8 02h
; 10 03h
; 18 04h
;if SRAMs in toggle burst mode, then
;L1 will be filled with:
; byte data
; 0 03h
; 8 02h
; 10 01h
; 18 04h

;-----Compare the cache line to the Burst Pattern Table above. The
;signature of the pattern will determine if the burst was
;linear or toggle.
mov     al, byte ptr ds:[10h]  ;check byte ds:[10] in the L1
cmp     al,3h                 ;it will be a 1 if toggle mode
pop     ds                    ;it will be a 3 if linear mode
jnz     not_linear

is_linear:
mov     dx,offset Msg_yes     ;SRAMs in linear burst mode
jmp     over_not
not_linear:
mov     dx,offset Msg_no      ;SRAMs in toggle burst mode
over_not:
wbinvd

;-----disable L1 internal cache
call    cache_off

```

continued

Figure 9

```

;-----restore chipset to toggle mode burst order
mov     al,51h                ;al=reg to read
call    r_pci_reg            ;READ al=reg contents
mov     ah,al
and     ah,0f7h              ;MODIFY clr linbrst bit
mov     al,51h
call    w_pci_reg            ;WRITE

call    dis_linbrst

;-----restore L1 caching
call    cache_on

done:
popf

;-----display a msg using a DOS call
mov     ax,seg Msg_2
mov     ds,ax
mov     ah,9h                ;print string function
int     21h                  ;DOS int

;-----return to the operating system
.EXIT

comment~*****
function      r_pci_reg
purpose       read the pci register at the index in al
inputs        al= the index of the pci register
returns       al= the data read from the pci reg
*****
r_pci_reg PROC

pushf
push     eax
push     dx
cli

mov     dx,index_port
and     eax,0FFh
or      eax,pci_index
out     dx,eax

and     al,3
mov     dx,data_port
add     dl,al
in      al,dx
xchg    al,b1                ;preserve rtn value

mov     eax,pci_index

```

continued

Figure 9

```

mov     dx,index_port
out     dx,eax

pop     dx
pop     eax
popf

xchg   al,b1
ret

r_pci_reg ENDP

comment~*****
function      w_pci_reg
inputs       al= the index of the pci register ah= the data to write
outputs      modifies chipset registers directly
returns      none
*****~
w_pci_reg proc

pushf
push     eax
push     bx
push     dx
cli

mov     bx,ax                ;preserve input value(s)

mov     dx,index_port
and     eax,0FFh
or      eax,pci_index
out     dx,eax

and     al,3
mov     dx,data_port
add     dl,al
mov     al,bh                ;recall data to write
out     dx,al

mov     eax,pci_index
mov     dx,index_port
out     dx,eax

pop     dx
pop     bx
pop     eax
popf
ret
w_pci_reg ENDP

```

continued

Figure 9

```

comment~*****
function      en_linbrst
purpose      enable the STST6x86 linbrst bit
inputs       none
outputs      modifies the STST6x86 CPU registers directly
returns      none
*****~
en_linbrst PROC

mov     ax,0C3C3h           ;set LINBRST
out     22h,a1
in      al,23h
xchg    ah,a1
or      ah,4
out     22h,a1
xchg    ah,a1
out     23h,a1

ret
en_linbrst ENDP

comment~*****
function      dis_linbrst
purpose      disable the STST6x86 linbrst bit
inputs       none
outputs      modifies the STST6x86 CPU registers directly
returns      none
*****~
dis_linbrst PROC

mov     ax,0C3C3h
out     22h,a1
in      al,23h
xchg    ah,a1
and     ah,0fbh           ;clear the linbrst bit
out     22h,a1
xchg    ah,a1
out     23h,a1

ret
dis_linbrst ENDP

comment~*****
function      cache_off
purpose      disables the L1 cache
inputs       none
returns      none
*****~
cache_off PROC

```

continued

Figure 9

```

pushf
push  eax
cli
mov   eax,cr0
or    eax,60000000h
mov   cr0,eax
wbinvd
jmp   $+2
pop   eax
popf
ret
cache_off ENDP

comment~*****
function      cache_on
purpose       enables the L1 cache
inputs        none
returns       none
*****~
cache_on PROC
pushf
push  eax
cli
mov   eax,cr0
and   eax,9FFFFFFFh
mov   cr0,eax
pop   eax
popf
ret
cache_on ENDP

END

```

Figure 9

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